

Multitasking Basics

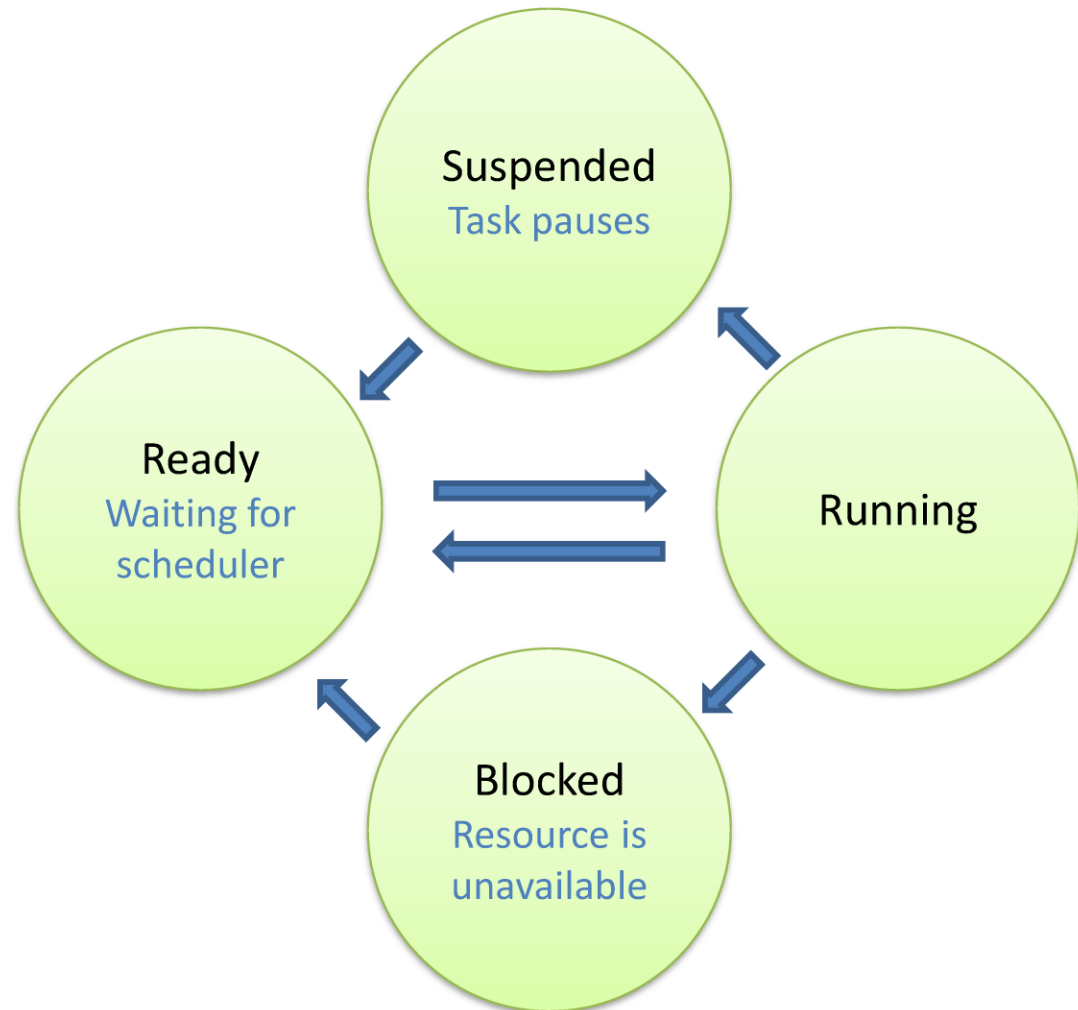
Networks and Embedded Software

Module 6.2.1

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Scheduler (1)

- Task states
 - Ready
Dormant
 - Running
 - Suspended
Task pauses
 - Blocked
Resource is unavailable
 - Waiting



Scheduler (2)

- Task control: FreeRTOS example

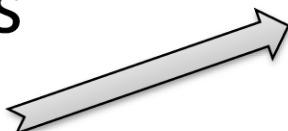

- Task control

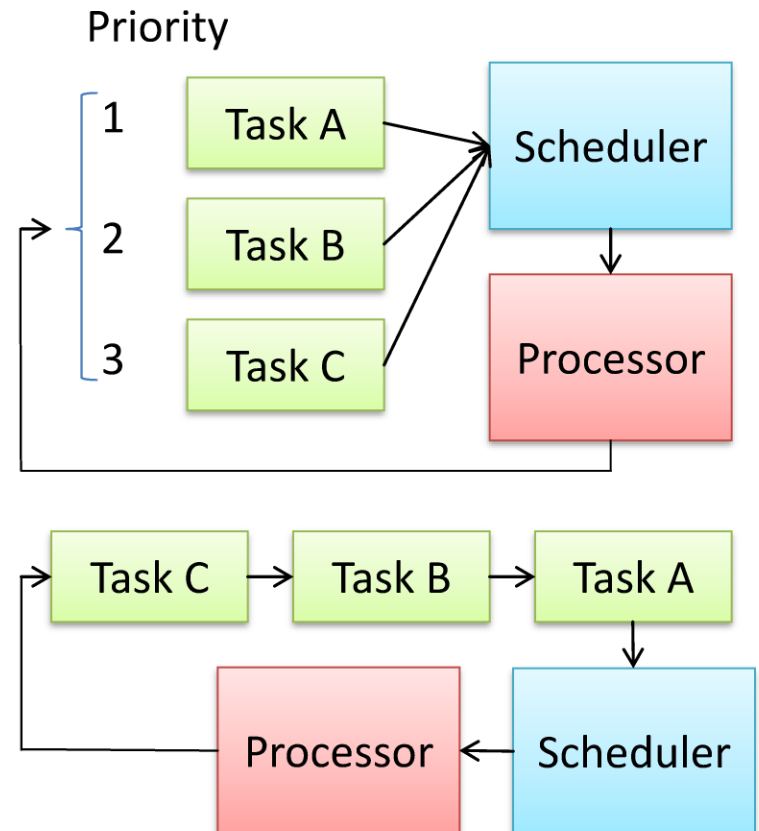
- `void vTaskSuspend(TaskHandle_t xTaskToSuspend);`
 - `void vTaskResume(TaskHandle_t xTaskToResume);`
 - `void vTaskDelay(const TickType_t xTicksToDelay);`

- Example

```
void vTask (void* pvParameters) {  
    while (1) {  
        ...  
        // Suspend for 500 ms  
        vTaskDelay(pdMS_TO_TICKS(500));  
    }  
}
```

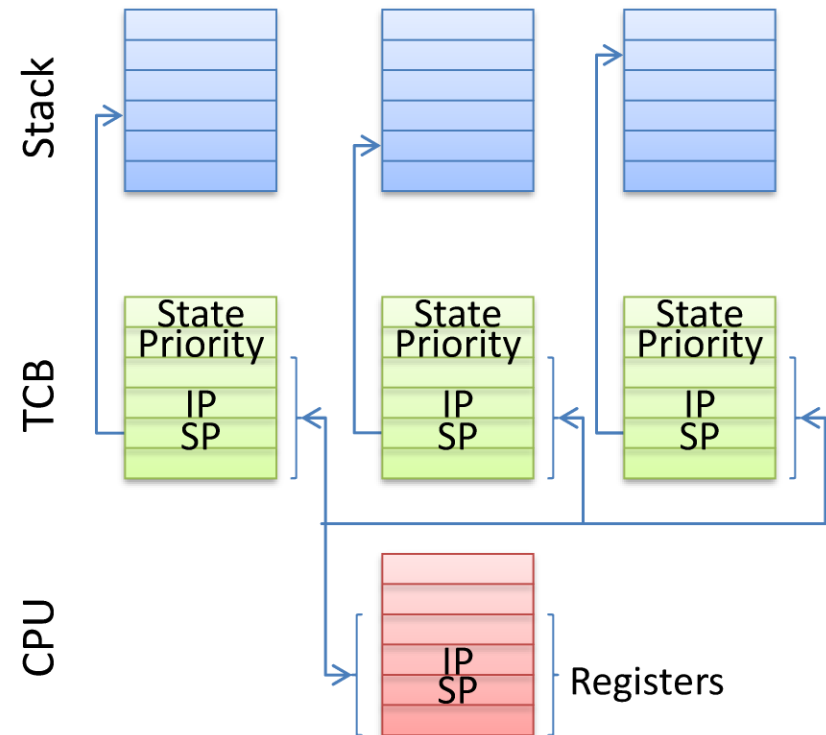
Scheduler (3)

- Enables multitasking
- Assigns time slices
- Selects next task to run
- Basic algorithms
 - Priority based 
 - Round-robin 



Scheduler (4)

- Context Switch
 - Context must be saved
 - Registers
 - Instruction Pointer
 - Stack Pointer
 - Task State
 - Task Priority
 - Context is saved in Task Control Block



Scheduler (5)

- Timing
 - Timing of tasks is unknown
 - Implementation of scheduler is unknown
 - Interrupts can influence scheduling
 - Tasks may be blocked by external devices
 - No assumption on timing must be made
 - Algorithms must not depend on timing
 - Result of the algorithm must not depend on the execution sequence of the different tasks

Race Conditions (1)

- Pre-emption
 - Tasks can be interrupted at any time
 - Interruption may corrupt data
 - Software must be thread-safe

```
int temp;  
void swap(int *a, int *b)  
{ // not thread-save  
    temp = *a;  
    *a = *b;  
    *b = temp;  
}
```

```
void swap(int *a, int *b)  
{ // thread-save  
    int temp;  
    temp = *a;  
    *a = *b;  
    *b = temp;  
}
```

Race Conditions (2)

- Basic concepts
 - Unexpected results
 - Reason
 - Result depends on the timing of tasks
 - The timing of tasks is unknown
 - Precondition
 - Multitasking (at least two concurring tasks)
 - Common resource (data, hardware)
 - Modification of the resource (write access)

Race Conditions (3)

- Example 1 (common resource is hardware)

Tick	Task 1	Printer	Task 2
	<code>print("abc");</code>		<code>print("123");</code>
0	<code>out('a');</code>	a	
1	<code>out('b');</code>	ab	
2		ab1	<code>out('1');</code>
3	<code>out('c');</code>	ab1c	
4		ab1c2	<code>out('2');</code>
5		ab1c23	<code>out('3');</code>

Pre-emption

Pre-emption

Unexpected result

Race Conditions (4)

- Example 2 (common resource is data: data race)

Tick	Task 1			Common	Task 2		
	swap(4,5);	a=4	b=5	temp=?	a=1	b=2	swap(1,2);
0	temp = a;	a=4	b=5	temp=4	a=1	b=2	
1	a = b;	a=5	b=5	temp=4	a=1	b=2	
2		a=5	b=5	temp=1	a=1	b=2	temp = a;
3		a=5	b=5	temp=1	a=2	b=2	a = b;
4		a=5	b=5	temp=1	a=2	b=1	b = temp;
5	b = temp;	a=5	b=1	temp=1			
Task 1 lost the race: unexpected result!					Task 2 won the race!		

Pre-emption

Pre-emption

Race Conditions (5)

- Remedies

- No common resources

- Not always possible
 - Hardware
 - Communication

- No multitasking

- Prevent pre-emption
 - Performance issues
 - Must be very small

```
int temp;
void swap(int *a, int *b)
{
    // now thread-save
    taskENTER_CRITICAL();
    temp = *a;
    *a = *b;
    *b = temp;
    taskEXIT_CRITICAL();
}
```

